

FIG. I

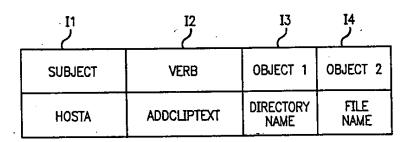


FIG. 2

ſ							
£ (PROCESSING CONTENT	MOVING THE MOUSE TO THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	PRESSING DOWN THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	RELEASING UP THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	DOUBLE CLICK OF THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES *	PRESSING DOWN THE RIGHT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	RELEASING UP THE RIGHT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES
* ✓	OBJECT	*	*	*	*	+	*
E	OBJECT 1 OBJECT 2	•	•	*	*	*	*
72	VERB	MOUSEMOVE	LBUTTONDOWN	LBUTTONUP	LBUTTONDBLCLK	RBUTTONDOWN	RBUTTONUP
۲	SUBJECT	*	HOSTA .	HOSTB	HOSTC	*	*

TITLE: NETWORK SYSTEM AND OBJECT COOPERATION THEREIN

INVENTORS: Makoto OKADA, et al. SERIAL NO.: Unassigned DOCKET NO.: 21.1886C

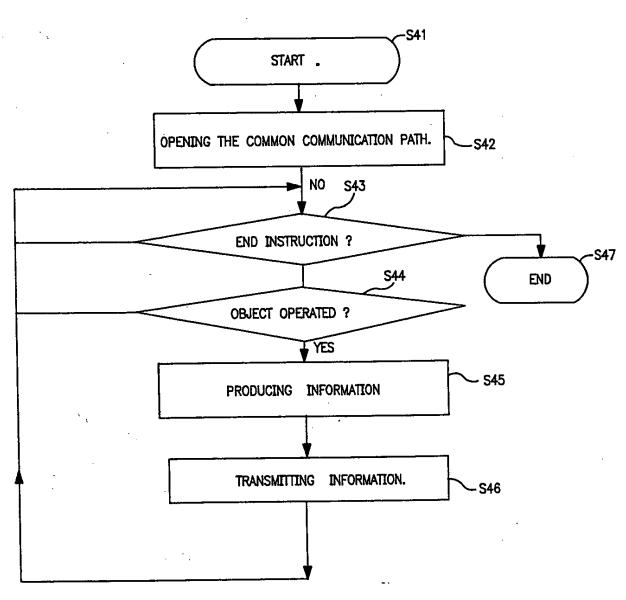


FIG. 4

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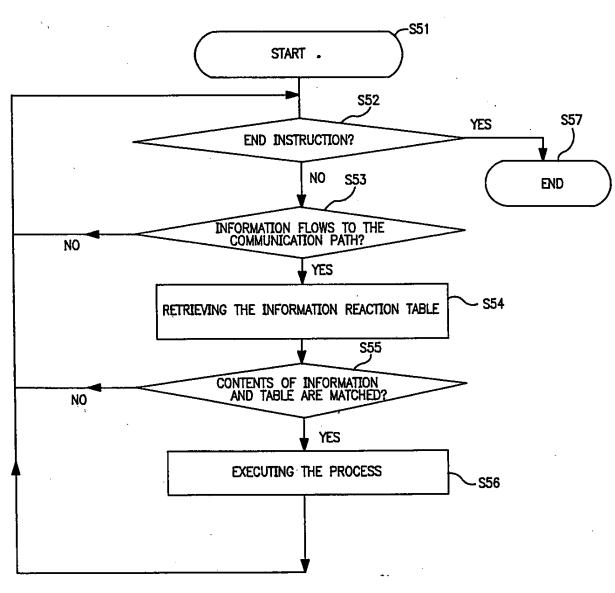


FIG. 5

DOCKET NO.: 21.1886C

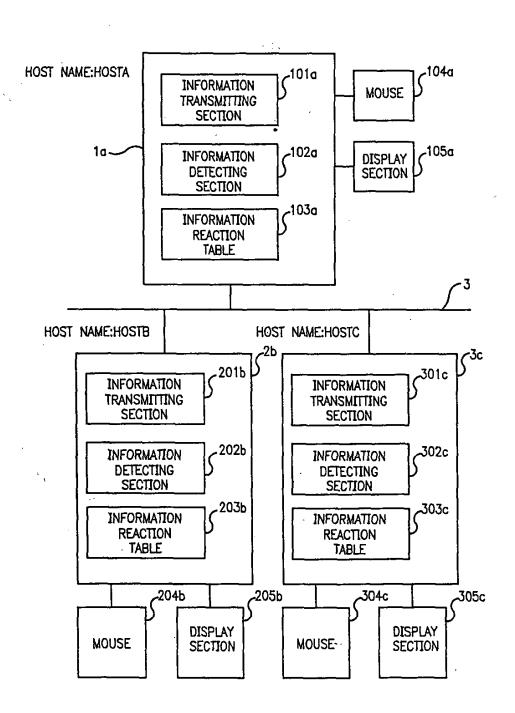


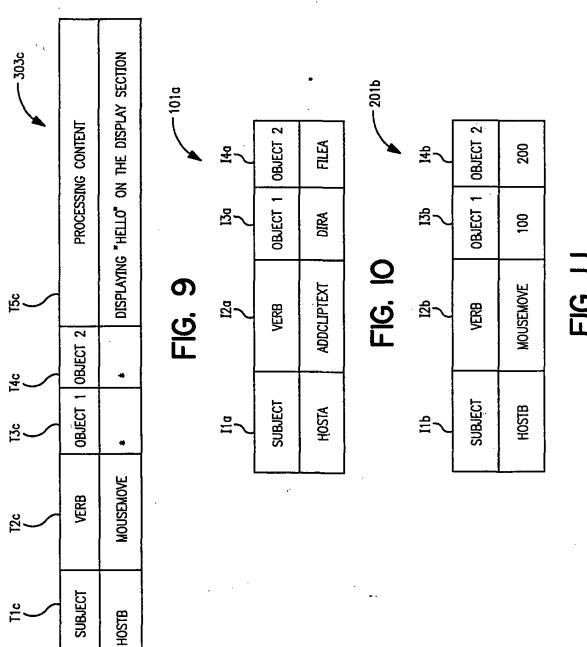
FIG. 6

TITLE: NETWORK SYSTEM AND OBJECT COOPERATION THEREIN INVENTORS: Maketo OKADA, et al.

SERIAL NO.:	Unassigned
DOCKET NO .:	21.1886C

1				, , , , , , , , , , , , , , , , , , ,
T5b	PROCESSING CONTENT	COPYING A FILE DEFINING OBJECT 1 AND OBJECT 2 AS DIRECTORY NAME AND FILE NAME TO THE CLIPBOARD	COPYING A FILE DEFINING OBJECT 1 AND OBJECT 2.4S DIRECTORY NAME AND FILE NAME TO THE CLIPBOARD	COPYING A FILE DEFINING OBJECT 1 AND OBJECT 2 AS DIRECTORY NAME AND FILE NAME TO THE CLIPBOARD
14b	OBJECT 2	*	*	46
T3b	OBJECT 1 OBJECT 2	*	*	*
T2b	VERB	ADDCLIPFILE	ADDCLIPTEXT	ADDCLIPMETAFILE:
T1b	SUBJECT	*	*	*

FIG. 8



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T5b1	PROCESSING CONTENT	DISPLAYING THE CONTENT OF INQUIRY BY DRIVING QUESTION AND ANSWER SYSTEM	DISPLAYING THE CONTENT OF DECISION REQUEST BY DRIVING DECISION MAKING SYSTEM	NOTIFYING THE IDLE CONDITION BY DRIVING SCHEDULE MANAGEMENT SYSTEM	NOTIFYING THE IDLE CONDITION BY DRIVING SCHEDULE MANAGEMENT SYSTEM
T4b1	OBJECT 2		DECISION-MAKING	*	*
13b1	OBJECT 1	*	*	*	••
12b1	VERB	INQUIRY	DECISION	MEETING	MEETING
Tlb1	SUBJECT	*	*	HOSTA	ноѕтс

		Ţ-,		<u>,</u>
T5c1	PROCESSING CONTENT	DISPLAYING THE CONTENT OF INQUIRY BY DRIVING QUESTION AND ANSWER SYSTEM	NOTIFYING THE IDLE CONDITION BY DRIVING SCHEDULE MANAGEMENT SYSTEM	NOTIFYING THE IDLE CONDITION BY DRIVING SCHEDULE MANAGEMENT SYSTEM
74c1	OBJECT 2	*	**	*
T3c1 T	OBJECT 1	CLIENT/SERVER SYSTEM	*	*
T2c1	VERB	INQUIRY	MEETING	MEETING
T1c1	SUBJECT	*	HOSTA	ноѕтв

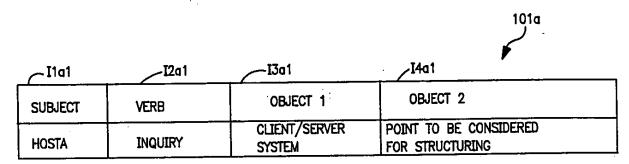


FIG. 14

			101a
_I1a2		_13a2	[4a2
SUBJECT	VERB	OBJECT 1	OBJECT 2
HOSTA	DECISION	DECISION- MAKING	ACQUISITION OF FACILITY

FIG. 15

			101a
_I1a3		I3a3	
SUBJECT	VERB	OBJECT 1	OBJECT 2
HOSTA	MEETING	PROCESS CONFERENCE	PROJECT: A

FIG. 16

		CONDITION	REACTION OF THE OTHER	טבודו זער מד אוואפורזס
	FLAG NAME	OF FLAG	OBJECT	יארוסואותאס וס ווויר נודדת
	MEODM	0	REACTION	NONE
T6 7			NON-REACTION	MACHING TABLE VALUE
(0	REACTION	NONE
5 -	FORCE		REACTION	RETURNING VALUE AFTER EXECUTION OF MACHING FUNCTION

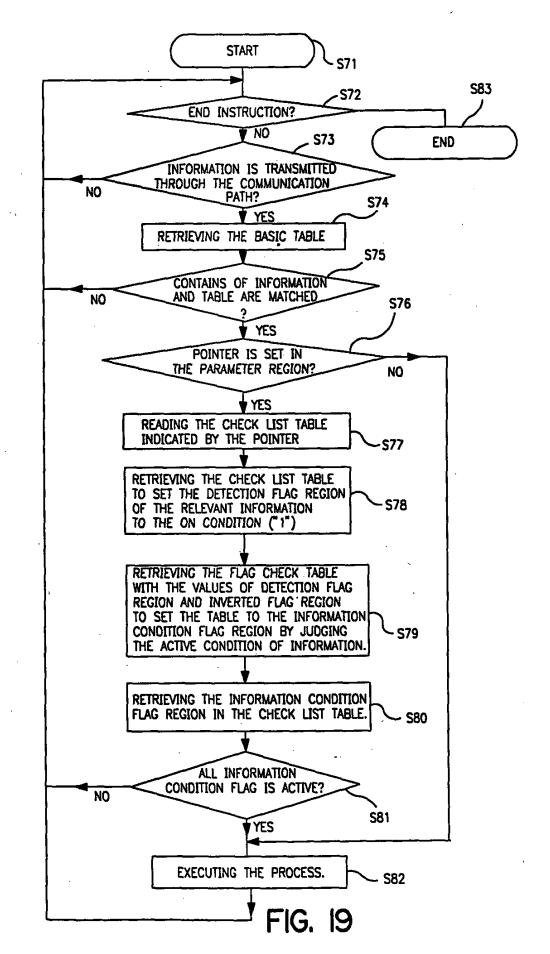
103a, 203b, 303c

103a,	203b, 30	3c					
<u>រា1</u>	BASIC TAE	LE		· - · · · · · · · · · · · · · · · · · ·			
	лі–1	√II-2	л1−3_	_ л	[-4	J∏-5	√J∏-6
SUBJE	CT	VERB	OBJECT 1	OBJECT		CESSING TENT	PARAMETER
SUBJE	CT-A	VERB-A1	•	*	ACT	ION-A1	PARAM-A1
SUBJE	CT-B	VERB-B1	*	*	ACT.	ION-B1	POINTER-a
SUBJE	CT-C	VER8-C1	*	*	ACT	ION-C1	POINTER- a
SUBJE	CT-B	VERB-82	*	*	ACT	ION-B2	POINTER-B
SUBJE	CT-C	VERB-D1		•	ACTI	ION-D1	POINTER- β
POINTER-	K LIST TAI		JT2-3a OBJECT 1		JT2-50 DETECTED FLAG	JT2-60 INVERTED FLAG	JT2-7a INFORMATION CONDITION FLAG
	SUBJECT-	·B VERB-B1	*	*	0	0	INACTIVE
	SUBJECT-	C VERB-C1	*	•	0	0	INACTIVE
POINTER-	β JT2-11 SUBJECT	VERB	JT2-36 OBJECT 1	ЛТ2—4b ОВЈЕСТ 2	JT2-5b DETECTED FLAG	JT2-6b INVERTED FLAG	JT2-7b INFORMATION CONDITION FLAG
	SUBJECT-	-B VERBB2	*		o	0	INACTIVE
	SUBJECT-	-D VERBD1	*	. * .	0	1	ACTIVE
<u>113</u>	DETECTED FLAG	HECK TABLE INVERTED FLAG	O INACTIVE	1 ACTIVE		<u> </u>	<u> </u>
					1		
		<u> </u>	ACTIVE	INACTIVE	-	•	

FIG. 18

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 $\frac{JT2}{POINTER-\alpha}$ CHECK LIST TABLE

JT2-1c	JT2-2c	JT2-3c	JT2-4c	J72-5c	JT2-6c	JT2-7c	JT2-8c
Subject	VERB	OBJECT 1	OBJECT 2	DETECTED FLAG	INVERTED	INFORMATION CONDITION FLAG	REACTION
SUBJEC-B	VERB-B1	*	*	0	0	INACTIVE	100
SUBJECT-C	VERBC1	•	*	0	0	INACTIVE	0

